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IN THE CLAIMS

This listing of claims will replace all prior versions, and listing, of claims in the application:

- 1 1. (previously presented) Apparatus for use in a video image de-interlacer
2 comprising:
3 a frame interpolator for yielding a frame based luminance value for a missing pixel by
4 using frame based interpolation;
5 a field interpolator for yielding a field based luminance value for a missing pixel by
6 using field based interpolation;
7 a luminance difference unit for obtaining luminance value differences of pixels in
8 prescribed fields of an image in accordance with prescribed criteria;
9 a motion detector supplied with prescribed ones of said luminance value differences
10 for generating a motion metric value at a missing pixel and for filtering said pixel differences
11 to remove aliases under predetermined motion conditions;
12 a spatial median filter supplied with at least three of said motion metric values for
13 determining a median motion metric value and for removing random noise from said
14 luminance differences without creating spurious motion values; and
15 a controllable combiner supplied with said frame based luminance value and said
16 field based luminance value and being responsive to a representation of said median motion
17 metric value to controllably supply as an output a luminance value for said missing pixel,
18 wherein said controllable combiner, in response to said representation of said median motion
19 metric value indicating the image is still, outputs said frame based luminance value and, in
20 response to said representation of said median motion metric value indicating motion in the
21 image, outputs said field based luminance value.
- 1 2. (original) The apparatus as defined in claim 1 wherein said spatial median filter is a nine-
2 value spatial median filter.

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1 3. (canceled)

1 4. (previously presented) The apparatus as defined in claim 1 wherein said frame based
2 luminance value is generated by said frame interpolator in accordance with $C_0 = C_{-1}$, where
3 C_0 is the luminance value of the missing pixel in field f_0 and C_{-1} is the luminance value of
4 a pixel corresponding to the missing pixel in a last prior field f_{-1} relative to field f_0 , and
5 said field based luminance value is generated by said field interpolator in accordance with
6 $C_0 = \frac{(N_0 + S_0)}{2}$, where N_0 is the luminance value of a pixel above of and in the same field
7 f_0 as the missing pixel, and S_0 is the luminance value of a pixel below of and in the same
8 field f_0 as the missing pixel.

1 5. (original) The apparatus as defined in claim 1 wherein said luminance difference unit
2 generates a plurality of prescribed luminance value differences of pixels in prescribed fields
3 of the image, and said motion detector employs prescribed relationships of said luminance
4 value differences to generate said motion metric value.

1 6. (original) The apparatus as defined in claim 5 wherein said luminance difference unit
2 generates a first luminance difference value in accordance with $\Delta_c = |C_1 - C_{-1}|$, where C_{-1} is
3 a luminance value of a pixel corresponding to the missing pixel in the last prior field f_{-1}
4 relative to a field f_0 including the missing pixel and C_1 is a luminance value of a pixel
5 corresponding to the missing pixel in field f_1 , and generates at least a second luminance
6 difference value in accordance with $\Delta_o = \left| \frac{N_0 + S_0}{2} - \frac{N_{-2} + S_{-2}}{2} \right|$, where N_0 is a luminance
7 value of a pixel above of and in the same field f_0 as the missing pixel, S_0 is a luminance
8 value of a pixel below of and in the same field f_0 as the missing pixel, N_{-2} is a luminance
9 value of a pixel above of the missing pixel and in the second prior field f_{-2} relative to the
10 field f_0 including the missing pixel and S_{-2} is a luminance value of a pixel below of the

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11 missing pixel, and in the second prior field f_{-2} relative to the field f_0 including the missing
12 pixel.

1 7. (original) The apparatus as defined in claim 6 wherein said motion detector generates said
2 motion metric value in accordance with $\Delta = \max(\Delta_c, \Delta_n)$, where Δ is said motion metric
3 value.

1 8. (original) The apparatus as defined in claim 5 wherein said luminance difference unit
2 generates a first luminance difference value in accordance with $\Delta_c = |C_1 - C_{-1}|$, where C_{-1} is
3 a luminance value of a pixel corresponding to the missing pixel in the last prior field f_{-1}
4 relative to a field f_0 including the missing pixel and C_1 is a luminance value of a pixel
5 corresponding to the missing pixel in field f_1 , generates a second luminance difference value
6 in accordance with $\Delta_n = |N_0 - N_{-2}|$, where N_0 is a luminance value of a pixel above of and
7 in the same field f_0 as the missing pixel and N_{-2} is a luminance value of a pixel above of the
8 missing pixel and in the second prior field f_{-2} relative to the field f_0 including the missing
9 pixel, and generates at least a third luminance difference value in accordance with
10 $\Delta_s = |S_0 - S_{-2}|$, where S_0 is a luminance value of a pixel below of and in the same field f_0 as
11 the missing pixel and S_{-2} is a luminance value of a pixel below of the missing pixel and in
12 the second prior field f_{-2} relative to the field f_0 including the missing pixel.

1 9. (original) The apparatus as defined in claim 8 wherein said motion detector generates said
2 motion metric value in accordance with $\Delta = \max(\Delta_c, \min(\Delta_n, \Delta_s))$, where Δ is said motion
3 metric value.

1 10. (original) The apparatus as defined in claim 1 further including a look-up table including
2 blending factor values related to said median motion metric values and being responsive to
3 said median motion metric value from said spatial median filter for supplying as an output a

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4 corresponding blending factor value as said representation of said median motion metric
5 value.

1 11. (original) The apparatus as defined in claim 10 wherein said controllable combiner is
2 responsive to said blending factor for supplying as an output a luminance value for said
3 missing pixel in accordance with $C_0 = \alpha \frac{(N_0 + S_0)}{2} + (1 - \alpha)C_{-1}$, where C_0 is the luminance
4 value of the missing pixel in field f_0 , C_{-1} is the luminance value of a pixel corresponding to
5 the missing pixel in a last prior field f_{-1} relative to field f_0 , N_0 is the luminance value of a
6 pixel above of and in the same field f_0 as the missing pixel, S_0 is the luminance value of a
7 pixel below of and in the same field f_0 as the missing pixel and α is the blending factor.

1 12. (original) The apparatus as defined in claim 11 wherein said luminance difference unit
2 generates a plurality of prescribed luminance value differences of pixels in prescribed fields
3 of the image, and said motion detector employs prescribed relationships of said luminance
4 value differences to generate said motion metric value.

1 13. (original) The apparatus as defined in claim 12 wherein said luminance difference unit
2 generates a first luminance difference value in accordance with $\Delta_c = |C_1 - C_{-1}|$, where C_{-1} is
3 a luminance value of a pixel corresponding to the missing pixel in the last prior field f_{-1}
4 relative to a field f_0 including the missing pixel and C_1 is a luminance value of a pixel
5 corresponding to the missing pixel in field f_1 , and generates at least a second luminance
6 difference value in accordance with $\Delta_o = \left| \frac{N_0 + S_0}{2} - \frac{N_{-2} + S_{-2}}{2} \right|$, where N_0 is a luminance
7 value of a pixel above of and in the same field f_0 as the missing pixel, S_0 is a luminance
8 value of a pixel below of and in the same field f_0 as the missing pixel, N_{-2} is a luminance
9 value of a pixel above of the missing pixel and in the second prior field f_{-2} relative to the
10 field f_0 including the missing pixel and S_{-2} is a luminance value of a pixel below of the

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11 missing pixel, and in the second prior field f_{-2} relative to the field f_0 including the missing
12 pixel.

1 14. (original) The apparatus as defined in claim 13 wherein said motion detector generates
2 said motion metric value in accordance with $\Delta = \max(\Delta_c, \Delta_s)$, where Δ is said motion metric
3 value.

1 15. (original) The apparatus as defined in claim 10 wherein said luminance difference unit
2 generates a first luminance difference value in accordance with $\Delta_c = |C_1 - C_{-1}|$, where C_{-1} is
3 a luminance value of a pixel corresponding to the missing pixel in the last prior field f_{-1}
4 relative to a field f_0 including the missing pixel and C_1 is a luminance value of a pixel
5 corresponding to the missing pixel in field f_1 , generates a second luminance difference value
6 in accordance with $\Delta_s = |N_0 - N_{-2}|$, where N_0 is a luminance value of a pixel above of and
7 in the same field f_0 as the missing pixel and N_{-2} is a luminance value of a pixel above of the
8 missing pixel and in the second prior field f_{-2} relative to the field f_0 including the missing
9 pixel, and generates at least a third luminance difference value in accordance with
10 $\Delta_s = |S_0 - S_{-2}|$, where S_0 is a luminance value of a pixel below of and in the same field f_0 as
11 the missing pixel and S_{-2} is a luminance value of a pixel below of the missing pixel and in
12 the second prior field f_{-2} relative to the field f_0 including the missing pixel.

1 16. (original) The apparatus as defined in claim 15 wherein said motion detector generates
2 said motion metric value in accordance with $\Delta = \max(\Delta_c, \min(\Delta_s, \Delta_s))$, where Δ is said
3 motion metric value.

1 17. (previously presented) Apparatus for use in a video image dc-interlacer comprising:
2 a frame interpolator for yielding a frame based luminance value for a missing pixel by
3 using frame based interpolation;

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4 a field interpolator for yielding a field based luminance value for a missing pixel by
5 using field based interpolation;
6 a luminance difference unit for obtaining luminance value differences of pixels in
7 prescribed fields of an image in accordance with prescribed criteria;
8 a motion detector supplied with prescribed ones of said luminance value differences
9 for generating a motion metric value at a missing pixel and for filtering said pixel differences
10 to remove aliases under predetermined motion conditions;
11 a look-up table including blending factor values related to said motion metric values
12 and being responsive to supplied motion metric values for supplying as an output
13 corresponding blending factor values;
14 a spatial median filter supplied with at least three of said blending factor values for
15 determining a median motion metric value and for removing random noise from said
16 luminance differences without creating spurious motion values; and
17 a controllable combiner supplied with said frame based luminance value and said
18 field based luminance value and being responsive to a said median blending factor value to
19 controllably supply as an output a luminance value for said missing pixel,
20 wherein said controllable combiner, in response to said representation of said median motion
21 metric value indicating the image is still, outputs said frame based luminance value and, in
22 response to said representation of said median motion metric value indicating motion in the
23 image, outputs said field based luminance value.

1 18. (original) The apparatus as defined in claim 17 wherein said spatial median filter is a
2 nine-value spatial median filter.

1 19. (canceled)

1 20. (original) The apparatus as defined in claim 17 wherein said controllable combiner is
2 responsive to said blending factor for supplying as an output a luminance value for said
3 missing pixel in accordance with $C_0 = \alpha \frac{(N_0 + S_0)}{2} + (1 - \alpha)C_{-1}$, where C_0 is the luminance
4 value of the missing pixel in field f_0 , C_{-1} is the luminance value of a pixel corresponding to

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5 the missing pixel in a last prior field f_{-1} relative to field f_0 , N_0 is the luminance value of a
6 pixel above of and in the same field f_0 as the missing pixel, S_0 is the luminance value of a
7 pixel below of and in the same field f_0 as the missing pixel and α is the blending factor.

1 21. (original) The apparatus as defined in claim 20 wherein said luminance difference unit
2 generates a plurality of prescribed luminance value differences of pixels in prescribed fields
3 of the image, and said motion detector employs prescribed relationships of said luminance
4 value differences to generate said motion metric value.

1 22. (original) The apparatus as defined in claim 21 wherein said luminance difference unit
2 generates a first luminance difference value in accordance with $\Delta_c = |C_1 - C_{-1}|$, where C_{-1} is
3 a luminance value of a pixel corresponding to the missing pixel in the last prior field f_{-1}
4 relative to a field f_0 including the missing pixel and C_1 is a luminance value of a pixel
5 corresponding to the missing pixel in field f_1 , and generates at least a second luminance
6 difference value in accordance with $\Delta_s = \left| \frac{N_0 + S_0}{2} - \frac{N_{-2} + S_{-2}}{2} \right|$, where N_0 is a luminance
7 value of a pixel above of and in the same field f_0 as the missing pixel, S_0 is a luminance
8 value of a pixel below of and in the same field f_0 as the missing pixel, N_{-2} is a luminance
9 value of a pixel above of the missing pixel and in the second prior field f_{-2} relative to the
10 field f_0 including the missing pixel and S_{-2} is a luminance value of a pixel below of the
11 missing pixel, and in the second prior field f_{-2} relative to the field f_0 including the missing
12 pixel.

1 23. (original) The apparatus as defined in claim 22 wherein said motion detector generates
2 said motion metric value in accordance with $\Delta = \max(\Delta_c, \Delta_s)$, where Δ is said motion metric
3 value.

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1 24. (original) The apparatus as defined in claim 21 wherein said luminance difference unit
2 generates a first luminance difference value in accordance with $\Delta_c = |C_1 - C_{-1}|$, where C_{-1} is
3 a luminance value of a pixel corresponding to the missing pixel in the last prior field f_{-1}
4 relative to a field f_0 including the missing pixel and C_1 is a luminance value of a pixel
5 corresponding to the missing pixel in field f_1 , generates a second luminance difference value
6 in accordance with $\Delta_n = |N_0 - N_{-2}|$, where N_0 is a luminance value of a pixel above of and
7 in the same field f_0 as the missing pixel and N_{-2} is a luminance value of a pixel above of the
8 missing pixel and in the second prior field f_{-2} relative to the field f_0 including the missing
9 pixel, and generates at least a third luminance difference value in accordance with
10 $\Delta_s = |S_0 - S_{-2}|$, where S_0 is a luminance value of a pixel below of and in the same field f_0 as
11 the missing pixel and S_{-2} is a luminance value of a pixel below of the missing pixel and in
12 the second prior field f_{-2} relative to the field f_0 including the missing pixel.

1 25. (original) The apparatus as defined in claim 24 wherein said motion detector generates
2 said motion metric value in accordance with $\Delta = \max(\Delta_c, \min(\Delta_n, \Delta_s))$, where Δ is said
3 motion metric value.

1 26. (previously presented) A method for use in a video image de-interlacer comprising the
2 steps of:
3 frame interpolating to yield a frame based luminance value for a missing pixel by
4 using frame based interpolation;
5 field interpolating to yield a field based luminance value for a missing pixel by using
6 field based interpolation;
7 obtaining luminance value differences of pixels in prescribed fields of an image in
8 accordance with prescribed criteria;
9 filtering said pixel luminance value differences to remove aliases under
10 predetermined motion conditions;
11 in response to prescribed ones of said luminance value differences, generating a
12 motion metric value at a missing pixel;

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13 spatial median filtering at least three of said motion metric values to determine a
14 median motion metric value and to remove random noise from said luminance differences
15 without creating spurious motion values; and

16 controllably combining said frame based luminance value and said field based
17 luminance value and in response to a representation of said median motion metric value
18 controllably supplying as an output a luminance value for said missing pixel,
19 wherein said step of controllably combining, in response to said representation of said
20 median motion metric value indicating the image is still, outputs said frame based luminance
21 value and, in response to said representation of said median motion metric value indicating
22 motion in the image, outputs said field based luminance value.

1 27. (original) The method as defined in claim 26 wherein said step of spatial median filtering
2 employs a nine-value spatial median filter.

1 28. (canceled)

1 29. (previously presented) The method as defined in claim 26 wherein said step of frame
2 interpolating includes a step of generating said frame based luminance value in accordance
3 with $C_0 = C_{-1}$, where C_0 is the luminance value of the missing pixel in field f_0 and C_{-1} is
4 the luminance value of a pixel corresponding to the missing pixel in a last prior field f_{-1}
5 relative to field f_0 , and said step of field interpolating includes a step of generating said field
6 based luminance value in accordance with $C_0 = \frac{(N_0 + S_0)}{2}$, where N_0 is the luminance value
7 of a pixel above of and in the same field f_0 as the missing pixel, and S_0 is the luminance
8 value of a pixel below of and in the same field f_0 as the missing pixel.

1 30. (original) The method as defined in claim 26 wherein said step of obtaining luminance
2 value differences includes a step of generating a plurality of generating a motion metric value
3 includes a step of employing prescribed relationships of said luminance value differences to
4 generate said motion metric value.

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1 31. (original) The method as defined in claim 30 wherein said step of obtaining luminance
2 value differences includes a step of generating a first luminance difference value in
3 accordance with $\Delta_c = |C_1 - C_{-1}|$, where C_{-1} is a luminance value of a pixel corresponding to
4 the missing pixel in the last prior field f_{-1} relative to a field f_0 including the missing pixel
5 and C_1 is a luminance value of a pixel corresponding to the missing pixel in field f_1 , and a
6 step of generating at least a second luminance difference value in accordance with
7 $\Delta_s = \left| \frac{N_0 + S_0}{2} - \frac{N_{-2} + S_{-2}}{2} \right|$, where N_0 is a luminance value of a pixel above of and in the
8 same field f_0 as the missing pixel, S_0 is a luminance value of a pixel below of and in the
9 same field f_0 as the missing pixel, N_{-2} is a luminance value of a pixel above of the missing
10 pixel and in the second prior field f_{-2} relative to the field f_0 including the missing pixel and
11 S_{-2} is a luminance value of a pixel below of the missing pixel, and in the second prior field
12 f_{-2} relative to the field f_0 including the missing pixel.

1 32. (original) The method as defined in claim 31 wherein said step of generating a motion
2 metric value generates said motion metric value in accordance with $\Delta = \max(\Delta_c, \Delta_s)$, where
3 Δ is said motion metric value.

1 33. (original) The method as defined in claim 30 wherein said step of obtaining luminance
2 value differences includes a step of generating a first luminance value in accordance with
3 $\Delta_c = |C_1 - C_{-1}|$, where C_{-1} is a luminance value of a pixel corresponding to the missing pixel
4 in the last prior field f_{-1} relative to a field f_0 including the missing pixel and C_1 is a
5 luminance value of a pixel corresponding to the missing pixel in field f_1 , a step of generating
6 a second luminance difference value in accordance with $\Delta_n = |N_0 - N_{-2}|$, where N_0 is a
7 luminance value of a pixel above of and in the same field f_0 as the missing pixel and N_{-2} is
8 a luminance value of a pixel above of the missing pixel and in the second prior field f_{-2}
9 relative to the field f_0 including the missing pixel, and a step of generating at least a third

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10 luminance difference value in accordance with $\Delta_s = |S_0 - S_{-2}|$, where S_0 is a luminance
11 value of a pixel below of and in the same field f_0 as the missing pixel and S_{-2} is a
12 luminance value of a pixel below of the missing pixel and in the second prior field f_{-2}
13 relative to the field f_0 including the missing pixel.

1 34. (original) The method as defined in claim 33 wherein said step of generating a motion
2 metric value includes a step of generating said motion metric value in accordance with
3 $\Delta = \max(\Delta_s, \min(\Delta_n, \Delta_r))$, where Δ is said motion metric value.

1 35. (original) The method as defined in claim 26 further including a step of employing a
2 look-up table including blending factor values related to said median motion metric values
3 and, in response to a supplied median motion metric value, supplying as an output a
4 corresponding blending factor value as said representation of said median motion metric
5 value.

1 36. (original) The method as defined in claim 35 wherein said step of controllably
2 combining, in response to said blending factor, supplying as an output a luminance value for
3 said missing pixel in accordance with $C_0 = \alpha \frac{(N_0 + S_0)}{2} + (1 - \alpha)C_{-1}$, where C_0 is the
4 luminance value of the missing pixel in field f_0 , C_{-1} is the luminance value of a pixel
5 corresponding to the missing pixel in a last prior field f_{-1} relative to field f_0 , N_0 is the
6 luminance value of a pixel above of and in the same field f_0 as the missing pixel, S_0 is the
7 luminance value of a pixel below of and in the same field f_0 as the missing pixel and α is
8 the blending factor.

1 37. (original) The method as defined in claim 36 wherein said step of obtaining luminance
2 value differences includes a step of generating a plurality of prescribed luminance value
3 differences of pixels in prescribed fields of the image, and said step of generating a motion

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- 4 metric value includes a step of employing prescribed relationships of said luminance value
5 differences to generate said motion metric value.

1 38. (original) The method as defined in claim 37 wherein said step of obtaining luminance
2 values differences includes a step of generating a first luminance difference value in
3 accordance with $\Delta_c = |C_1 - C_{-1}|$, where C_{-1} is a luminance value of a pixel corresponding to
4 the missing pixel in the last prior field f_{-1} relative to a field f_0 including the missing pixel
5 and C_1 is a luminance value of a pixel corresponding to the missing pixel in field f_1 , and a
6 step of generating at least a second luminance difference value in accordance with
7 $\Delta_s = \left| \frac{N_0 + S_0}{2} - \frac{N_{-2} + S_{-2}}{2} \right|$, where N_0 is a luminance value of a pixel above of and in the
8 same field f_0 as the missing pixel, S_0 is a luminance value of a pixel below of and in the
9 same field f_0 as the missing pixel, N_{-2} is a luminance value of a pixel above of the missing
10 pixel and in the second prior field f_{-2} relative to the field f_0 including the missing pixel and
11 S_{-2} is a luminance value of a pixel below of the missing pixel, and in the second prior field
12 f_{-2} relative to the field f_0 including the missing pixel.

1 39. (original) The method as defined in claim 38 wherein said step of generating a motion
2 metric value includes a step of generating said motion metric value in accordance with
3 $\Delta = \max(\Delta_c, \Delta_s)$, where Δ is said motion metric value.

1 40. (previously presented) The method as defined in claim 35 wherein said step of obtaining
2 luminance value differences includes a step of generating a first luminance difference value
3 in accordance with $\Delta_c = |C_1 - C_{-1}|$, where C_{-1} is a luminance value of a pixel corresponding
4 to the missing pixel in the last prior field f_{-1} relative to a field f_0 including the missing pixel
5 and C_1 is a luminance value of a pixel corresponding to the missing pixel in field f_1 , a step
6 of generating a second luminance difference value in accordance with $\Delta_n = |N_0 - N_{-2}|$, where
7 N_0 is a luminance value of a pixel above of and in the same field f_0 as the missing pixel and

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8 N_{-2} is a luminance value of a pixel above of the missing pixel and in the second prior field
9 f_{-2} relative to the field f_0 including the missing pixel, and a step of generating at least a
10 third luminance difference value in accordance with $\Delta_s = |S_0 - S_{-2}|$, where S_0 is a luminance
11 value of a pixel below of and in the same field f_0 as the missing pixel and S_{-2} is a
12 luminance value of a pixel below of the missing pixel and in the second prior field f_{-2}
13 relative to the field f_0 including the missing pixel.

1 41. (original) The method as defined in claim 40 wherein said step of generating a motion
2 metric value includes a step of generating said motion metric value in accordance with
3 $\Delta = \max(\Delta_e, \min(\Delta_n, \Delta_s))$, where Δ is said motion metric value.

1 42. (previously presented) A method for use in a video image de-interlacer comprising the
2 steps of:
3 frame interpolating to yield a frame based luminance value for a missing pixel by
4 using frame based interpolation;
5 field interpolating to yield a field based luminance value for a missing pixel by using
6 field based interpolation;
7 obtaining luminance value differences of pixels in prescribed fields of an image in
8 accordance with prescribed criteria;
9 filtering said pixel luminance value differences to remove aliases under
10 predetermined motion conditions;
11 in response to prescribed ones of said luminance value differences, generating a
12 motion metric value at a missing pixel;
13 in response to supplied motion metric values, utilizing a look-up table including
14 blending factor values related to said motion metric values to supply as an output
15 corresponding blending factor values;
16 spatial median filtering at least three of said blending factor values for determining a
17 median blending factor value and to remove random noise from said luminance differences
18 without creating spurious motion values; and

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19 controllably combining said frame based luminance value and said field based
20 luminance value and in response to said median blending factor value controllably supplying
21 as an output a luminance value for said missing pixel,
22 wherein said step of controllably combining includes a step, responsive to said median
23 blending factor value indicating the image is still, of outputting said frame based luminance
24 value, and a step, responsive to said median blending factor value indicating motion in the
25 image, of outputting said field based luminance value.

1 43. (original) The method as defined in claim 42 wherein said spatial median filter is a nine-
2 value spatial median filter.

1 44. (canceled)

1 45. (original) The method as defined in claim 42 wherein said step of combining includes a
2 step, responsive to said median blending factor, of supplying as an output a luminance value
3 for said missing pixel in accordance with $C_0 = \alpha \frac{(N_0 + S_0)}{2} + (1 - \alpha)C_{-1}$, where C_0 is the
4 luminance value of the missing pixel in field f_0 , C_{-1} is the luminance value of a pixel
5 corresponding to the missing pixel in a last prior field f_{-1} relative to field f_0 , N_0 is the
6 luminance value of a pixel above of and in the same field f_0 as the missing pixel, S_0 is the
7 luminance value of a pixel below of and in the same field f_0 as the missing pixel and α is
8 the blending factor.

1 46. (original) The method as defined in claim 45 wherein said step of obtaining luminance
2 value differences includes a step of generating a plurality of prescribed luminance value
3 differences of pixels in prescribed fields of the image, and said step of generating a motion
4 metric value includes a step of employing prescribed relationships of said luminance value
5 differences to generate said motion metric value.

1 47. (original) The method as defined in claim 46 wherein said step of obtaining luminance
2 value differences includes a step of generating a first luminance difference value in

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3 accordance with $\Delta_c = |C_1 - C_{-1}|$, where C_{-1} is a luminance value of a pixel corresponding to
 4 the missing pixel in the last prior field f_{-1} relative to a field f_0 including the missing pixel
 5 and C_1 is a luminance value of a pixel corresponding to the missing pixel in field f_1 , and a
 6 step of generating at least a second luminance difference value in accordance with
 7 $\Delta_o = \left| \frac{N_0 + S_0}{2} - \frac{N_{-2} + S_{-2}}{2} \right|$, where N_0 is a luminance value of a pixel above of and in the
 8 same field f_0 as the missing pixel, S_0 is a luminance value of a pixel below of and in the
 9 same field f_0 as the missing pixel, N_{-2} is a luminance value of a pixel above of the missing
 10 pixel and in the second prior field f_{-2} relative to the field f_0 including the missing pixel and
 11 S_{-2} is a luminance value of a pixel below of the missing pixel, and in the second prior field
 12 f_{-2} relative to the field f_0 including the missing pixel.

1 48. (original) The method as defined in claim 47 wherein said step of generating a motion
 2 metric value includes a step of generating said motion metric value in accordance with
 3 $\Delta = \max(\Delta_c, \Delta_o)$, where Δ is said motion metric value.

1 49. (original) The method as defined in claim 46 wherein said step of obtaining luminance
 2 value differences includes a step of generating a first luminance difference value in
 3 accordance with $\Delta_c = |C_1 - C_{-1}|$, where C_{-1} is a luminance value of a pixel corresponding to
 4 the missing pixel in the last prior field f_{-1} relative to a field f_0 including the missing pixel
 5 and C_1 is a luminance value of a pixel corresponding to the missing pixel in field f_1 , a step
 6 of generating a second luminance difference value in accordance with $\Delta_n = |N_0 - N_{-2}|$, where
 7 N_0 is a luminance value of a pixel above of and in the same field f_0 as the missing pixel and
 8 N_{-2} is a luminance value of a pixel above of the missing pixel and in the second prior field
 9 f_{-2} relative to the field f_0 including the missing pixel, and a step of generating at least a
 10 third luminance difference value in accordance with $\Delta_s = |S_0 - S_{-2}|$, where S_0 is a luminance
 11 value of a pixel below of and in the same field f_0 as the missing pixel and S_{-2} is a